# GENERATION OF DAMPED RESPONSE SPECTRA FROM <br> AN UNDAMPED RESPONSE SPECTRUM BY CONSTRAINED INTERPOLATION 

by

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## ABSTRACT

The calculation of damped response spectra can be greatly simplified if only approximate spectra are required. The procedure proposed here is based on the observations that the shape of damped response spectra are similar to that of the undamped spectrum of the same record, and that a highly damped spectrum is smoother, and of smaller average value than a spectrum corresponding to a lower percentage damping. Guided by these general properties of damped spectra, a fast, approximate algorithm has been empirically devised for the production of damped spectra from an undamped spectrum. The technique is basically one of constrained interpolation. It is general in that it is independent of the physical significance of the data to which it is applied. As the number of constraint points increases, the approximations converge to a desired solution, so that any required degree of precision can be obtained. Computational costs, which are typically of the order of $10 \%$ of the cost of direct integration, are low enough that the approach described here should be competative with all other techniques for most applications.

A commonly calculated function in earthquake engineering is the damped pseudo-relative velocity response spectrum (PSRV). Standard presentations usually include PSRVs corresponding to $0,2,5,10$, and 20 percent of critical damping. Typical examples and listings of computer programs for evaluating the PSRV integral are presented by Trifunac and Lee (1973). The calculations are long and the physical significance of the precise shape and position of the individual PSRV peaks are uncertain, and not generally used in subsequent calculations. The question then presents itself as to whether one cannot find some method of adequately approximating PSRV values in a less expensive manner.

A similar problem has been presented by Johnson (1973). He found an empirical algorithm that produces approximations to 5 percent critical PSRVs as a function of magnitude and epicentral distance. Wiggins (1964) averaged the observed response spectra of a number of records to construct an empirical description of the dependence of response spectra on magnitude and epicentral distance. The production of PSRV estimates by digital filtering has also been shown to be a viable alternative to direct integration of accelerograms (Beaudet and Wolfson (1970), Udwadia and Trifunac (1973)).

The general properties of PSRVs are illustrated in Figure 1. All the PSRV curves for a single record are similar in shape. The main differences between the PSRV curves for various damping values are a) the average absolute values decrease as damping increases, and b) the PSRVs become smoother as damping increases. The purpose of this paper is to show that these trends can be simply and explicitly defined and the resulting algorithm used in the production of PSRVs.

While a number of other empirical relations have been used by others for the production of approximate PSRVs, the present approach has a number of distinct advantages:

1) it is independent of event magnitude,
2) it is independent of the source spectrum,
3) it is independent of the structure between the source and receiver,
4) it is independent of epicentral distance,
5) it is valid for any frequency range required,
6) it iacorporates real observations of spectral character,
7) unusual events require no special treatment,
8) the approximations can be made as close as desired to the exact solution, and,
9) the accuracy / cost ratio. is higher than that of other approximate methods and the exact computations.

## Precision of PSRVs

PSRV $_{n}$ curves can be calculated for any desired periods $(T)$ for any desired percentage ( $n$ ) of critical damping. There are 91 points on each spectrum in Figure 1. The reliability of these points is uncertain. If the number of points on any of the curves in Figure 1 was to be increased, one would find that the spectra contain a significant amount of fine structure, and some of the points that appear to be at spectral peaks are actually on the side of a larger peak (w.G. IKilne, personal communication, 1974). Hudson (1972) has shown that the ground motions generated by an earthquake can vary significantly in a small area and that it is difficult to attribute the observed variations to any single site parameter. Hence, the value of a single, precisely calculated set of PSRV curves is, as yet, undefined in terms of the evaluation of seismic risk.

Figure 2 contains another example. The two solid curves were determined by joining every second point in the undamped spectrum (PSRV。) in Figure l, first for one set of points, then for the intermediate set. These two curves, therefore, should be equally valid spectral estimates and give a qualitative indication of the overall spectral reliability. In the limit, as the number of calculated PSRV values becomes very large, only a broad envelope, similar to the two dotted curves in Figure 2, is left. This concept is not new. Small, sharp, local peaks.in any spectrum are of questionable validity (Blackman and Tukey (1958), Fryer (1973), Currie (1974) so that the calculation of reliable spectra commonly includes some form of prewhitening or smoothing. The results of Iynch (1969), Blume (1969), Newmark, Blume and Kapur (1973), and Udwadia and Trifunac (1974) suggest that an envelope drawn roughly as in Figure 2 corresponds approximately to $\pm \sigma$.

Since it is apparently unrealistic to attempt to determine PSRVs to
a precision of greater than $\approx 0.2$ on a $\log$ scale (as a rough observation from the typical example in Figure 2), one is left with a relatively simple problem. A fast, sinple empirical algorithm for constructing PSRV values that lie within that, or any other desired, uncertainty is described in the following section.

## Constrained Interpolation

The task of finding a simple algorithm which describes a non-linear phenomenon is generally difficult. However, if the desired solution is known or closely approximated at some control points, a linearized interpolation between these points may be adequate to describe the entire solution provided that the control points are sufficiently close together. Since each point in a PSRV can be calculated explicitly and separately, control values can be obtained for any number of points.

The production of an approximate PSRV $_{n}$ begins with the calculation of the PSRV. For the purpose of the present paper, it is not necessary to calculate values for the large number of periods (91 in Trifunac and Lee (1973)) usually used since the $\operatorname{PSRV}_{n}$ s are smoother than the PSRV. Every second or third point is often sufficient, and there is, of course, a corresponding saving in computation costs.

The next step is to choose a number of control points such that the average spectral behavior is approximately linear between the points. Obvious choices are the two end points and the spectral maximum. For some well behaved spectra, 2 or 3 control points are sufficient, and the use of 5 points ensures satisfactory results for almost all cases. PSRV values are calculated for the control points by the usual integration method. These integrations are expensive so it is desireable to keep the number of control points as small as is consistent with the precision desired. From the arguments in the previous section, it is expected that the use of more than 7 points is rarely justified. The saving in computational costs in this step is one of the main advantages to the use of an approximate method. If only 5 rather than 91 integrals are required, the computational costs are reduced by approximately $94 \%$. The lost precision which accompanies this is, as
previously described, of doubtful significance.
Once control values have been determined for a particular damped spectrum, the major part of the required computational effort is complete as all intermediate values are obtained by interpolation. This interpolation is constrained so that the resulting curve passes through the control points and its shape is similar to that of the PSRV o over the same period range, but smoother.

Figure 3 aillustrates the interpolation algorithm used. Points 3 and 4 are two adjacent control points for a $\operatorname{PSRV}_{n}$ and the curve 1-2 is the PSRV。. In order to interpolate between points 3 and 4 , the curve 1-2 is weighted by the dimensionless linear weighting functions $w_{1}$ and $w_{2}$ as follows: $\operatorname{PSRV}_{n}\left(T_{i}\right)=\operatorname{PSRV}_{0}\left(T_{i}\right)-\left(A_{0}-C_{n}\right) W_{1}\left(T_{i}\right)-\left(B_{0}-D_{n}\right) W_{2}\left(T_{i}\right)$
where: $\operatorname{PSRV}_{n}\left(T_{i}\right)=$ the estimate of an $n \%$ critical damped PSRV value at $\operatorname{period} T_{i}$
$\operatorname{PSRV} .\left(T_{i}\right)=$ the calculated value of PSKV。 at period $T_{i}$
$A_{0}$, $B_{0}=$ the calculated $P S R V_{0}$ values at the control points
$C_{n}, D_{n}=$ the calculated $P_{n} V_{n}$ values at the control points
$\mathrm{T}_{i} \quad=$ any period between those of the control points
$W_{1}, W_{2}=$ the linear weighting functions, which have values between 0 and 1
$w_{1}=\left(L-I\left(T_{i}\right)\right) / L$
$w_{2} \quad=I\left(T_{i}\right) / L$
L $\quad=$ distance between the two control points
$I\left(T_{i}\right) \quad=$ distance from the first control point to the point $T_{i}$.
$I$ and $I\left(T_{i}\right)$ are in units of $\log _{10} T, W_{1}$ and $W_{2}$ are dimensionless, and all other quantities are in units of $\log _{10}$ PSRV.

The final step is to smooth the $\mathrm{PS}_{\mathrm{KV}}^{\mathrm{n}}$ curve. The amount of smoothing increases as the damping increases. The required iliter perators were constructed from a simple triangular filter ( $0.23,0.54,0.23$ ). The amounts of smooting for 2, 5, 10, and 20 percent critical damping were empirically Iound to be approximately equivalent to applying tis iilter 3, 7, 11, and. 15 times respectively. A illter approximating the smesthing for any jercentage critical damping between 0 and 20 can be determined by interpolation in Figure 3b.

This approach is general in that it can be applied to any set of curves which comprise a group with similar characteristics. As any number of control points can be used, the approximate solution can be made to approach a desired solution with any accuracy required.

## Examples

In order to test the applicability of constrained interpolation, seven data sets were taken from Volume III of the California Institute of Technology Earthquake Engineering Research Laboratory Report EERL 72-80. These data, which are described in Table l, were chosen because they represent a rather wide variety of PSRV shapes. Both vertical and horizontal components are included, although a consistent effect of orientation was neither expected nor observed.

Figures 4 to 10 contain results for seven examples. In each figure there are five solid curves, which, from top to bottom, are for $0,2,5,10$, and 20 percent critical damping. These curves were obtained from the EERL report described above and were determined by evaluating the PSRV integral for each of 91 period values on each curve. Superimposed on the bottom four curves are the results of spectral estimation by constrained interpolation between 5 equally spaced control points. Any ther reasenable criterion could be used to define control points witheut significantly affecting the results. Tie use of equally spaced points simply ensures that all parts of the PSRV curves are similarily constrained, and allows identical treatment -1. all cases. In these examples, no problem was experienced in obtaining estimates that lie within the physically reasonable limits described earlier. The approximate estimates are closest to the precise estimates for those PSRV curves which appear typical, such as those in Figures 4, 6, 7 and 10. The results in Figures 5, 9, and to a lesser degree, in Figure 8, are not as close to the precise values, but the general behaviors of the PSRV。s in these figures are peculiar, and rare. This problem can be simply overcome by using more control points for any case in which a high degree of non-linearity is suspected.

## Conclusions

A fast method for obtaining approximate damped PSRV curves from an undamped PSRV curve is described. The method involves the calculation of precise PSRV values at a few control points with constrained interpolation to estimate intermediate values. Computational savings, which are typically of the order of $90 \%$ of the cost of direct integration, are sufficient that an empirical approach such as that described here should be compet ${ }^{e}$ tive with more precise methods for many applications.

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## Table Caption

Table 1: list of the accelerograms used in the examples in Figures 4 to 10.

| Figure | Date | Time | CIT Identification | Component |
| :---: | :---: | :---: | :---: | :---: |
| 4 | May 18, 1940 | 2037 PST | IIIAOO1 | SOOE |
| 5 | May 18, 1940 | 2037 PST | IIIA001 | vert |
| 6 | Oct 07, 1951 | 2011 PST | IIIA002 | vert |
| 7 | Jul 21, 1952 | 0453 PDT | IIIA005 | S48E |
| 8 | Dec 21, 1954 | 1156 PST | IIIA008 | N79E |
| 9 | .Feb 09, 1956 | 0725 PST | IIIA012 | vert |
| 10 | Mar 22, 1957 | 1144 PST | IIIAO17 | N26E |

## Figure Captions

Figure 1 : A typical set of PSRV curves.

Figure 2 : Uncertainty in the undamped PSRV curve in Figure 1.

Figure 3a: Constrained interpolation. This figure illustrates the geometry of the quantities in the interpolation formula.

Figure 3b: The apparent smoothness of a damped response spectrum increases as the \% critical damping increases. The smoothing factor (S) of a particular filter operator is defined as the smoothing produced by repeated application (S times) of the 3-point operator described in the text.

Figure 4 : Figures 4 to 10 are similar. The solid curves are the results of precise calculations and the symbols are the results of constrained interpolation. For clarity, only the undamped PSRV curve is plotted at its actual position. The $2 \%$ damped curve is displaced downward by $0.1 \log _{10}$ PSRV units, the $5 \%$ curve by 0.2 , the $10 \%$ curve by 0.3 , and the $20 \%$ curve by 0.4 . The control points are indicated by the arrows.

Figure 5 : Precise and approximate PSRV estimates. See Table 1 and the caption beneath Figure 4.

Figure 6 : Precise and approximate PSRV estimates. See Table 1 and the caption beneath Figure 4.

Figure 7 : Precise and approximate PSRV estimates. See Table 1 and the caption beneath Figure 4.
Figure 8 : Precise and approximate PSRV estimates. See Table 1 and the caption beneath Figure 4.Figure 9 : Precise and approximate PSRV estimates. See Table 1 and thecaption beneath Figure 4.
Figure 10: Precise and approximate PSRV estimates. See Table 1 and thecaption beneath Figure 4.

## RESPONSE SPECTRUM

IMPERIAL VALLEY EARTHQUAKE MAY 18. 1940-2037 PST
11Ihool 40.001.0 el centro site imperial valley irrigation district comp sooe
damping values rre 0.2 . 5 , 10 and 20 percent of chitlgai


(....)


fig $3 b$


$f_{i q} 5$

fig6


$f_{i g} 8$



Fig 10

