



GEOLOGICAL SURVEY OF CANADA OPEN FILE 4187

Expedition report: MV *Anne S. Pierce*, 2000, German Bank, Scotian Shelf

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Table of Contents

1.	Introduction - <i>B.J. Todd</i> ...1
1.1	Cruise overview ...1
1.2	Scientific equipment layout ...1
2.	Cruise narrative - <i>B.J. Todd</i> ...10
3.	Navigation and positioning - <i>D.E. Beaver, S.S. MacCabe and P.E. Pledge</i> ...23
3.1	AGCNav and Regulus ...23
3.2	ORE Trackpoint II ...24
4.	Geophysical survey ...25
4.1	Overview - <i>B.J. Todd</i> ...25
4.2	Sidescan sonar system - <i>A. Atkinson</i> ...25
4.3	Huntec DTS system - <i>M. Uyesugi</i> ...27
4.4	Digital tape recording - <i>P.E. Pledge</i> ...28
5.	Geological sampling - <i>B.J. Todd and R. Murphy</i> ...34
6.	Appendices
6.1	Trackplot
6.2	Navigation files
6.3	Deck photographs
6.4	Sediment sample photographs
6.5	Benthos sample photographs

1. Introduction - *B.J. Todd*

1.1 Cruise overview

German Bank is located offshore southwestern Nova Scotia in the Gulf of Maine (Fig.1). Water depths range from less than 40 m to approximately 100 m. The bank has a rugged morphology, with areas of bedrock outcrop juxtaposed with basins filled with glacial and post-glacial sediments. A remarkable sequence of well-defined, parallel to sub-parallel southwest-northeast aligned moraines extends across the entire bank.

Geological Survey of Canada (Atlantic) (GSCA) cruise “2000 *Anne S. Pierce*” to German Bank took place from April 14-24, 2000 on board the 34.6 m-long MV *Anne S. Pierce* (Figs. 2, 3). The ship was mobilized and demobilized at the Deep Sea Trawler facility in Lunenburg, Nova Scotia.

The overall scientific objective of this cruise was to improve our understanding of the extent of exposed bedrock, the distribution of sediments and the glacial geomorphology on German Bank which, in turn, will lead to an improved interpretation of the geological history of the bank and the dynamics of modern sedimentation. Specific objectives of the cruise were to obtain acoustic geophysical data, sea floor sediment samples and seabed photographs. German Bank was previously surveyed using a Simrad 1000 multibeam system from the CCGS *Frederick G. Creed*. The multibeam data were collected and processed by the Canadian Hydrographic Service (CHS) in 1997, 1998 and 2000. The resulting bathymetric images were used for expedition planning and for the field survey.

The cruise was divided into two phases, the first phase being the geophysical survey, and the second phase being the sediment sampling and sea floor photography.

The *Anne S. Pierce* was operated under the direction of Captain Garth Hiltz; the captain and crew of the vessel ably assisted in the survey and the sampling (Table 1). Scientific staff are listed in Table 2.

1.2 Scientific equipment and layout

The layout of scientific equipment on board the *Anne S. Pierce* is illustrated in Figures 2, 4 and 5. The foredeck was not used and all survey equipment was located on the

afterdeck.

On the port afterdeck was the Trackpoint II boom pivot location (Figs. 2, 4). When the ship was travelling to and from German Bank, the boom was kept in the horizontal position illustrated. On site, but before the geophysical survey was underway, the boom was lowered so that the Trackpoint II beacon was under the water surface. The beacon extended below the draft of the ship when the boom was vertical, as illustrated in Figure 2A.

The geophysical equipment (sidescan sonar and Hunttec Deep Tow Seismic (DTS)) were deployed from the stern using an A-frame constructed expressly for this purpose by Clearwater Fine Foods Inc. (CFFI) (Figs. 2, 4, and photographs in Appendix 6.3). The sidescan was deployed from the port side of the stern and the Hunttec DTS was deployed from the center of the stern. The winches were powered by a compressor secured to the deck forward.

Geological sampling was carried out from the stern using the A-frame to deploy a van Veen grab sampler and the Benthos sea floor camera.

This report is intended to provide a description of day-to-day activities on board the ship, to provide an overview of technical aspects of the equipment used, and to present a summary of the geophysical and geological data obtained during the *Anne S. Pierce* expedition to German Bank. In the following narrative account of the day-to-day activities (Section 2), reference is made to instrumentation and data which are fully described in later sections of this cruise report.

We thank Michael Li and Edward King, both of GSCA, for insightful reviews of this expedition report and for supporting its publication in PDF format.

List of tables

- | | |
|----------|-----------------------------------------------|
| Table 1. | List of Clearwater Fine Foods Inc. personnel. |
| Table 2. | List of scientific personnel. |

List of figures

- | | |
|-----------|--------------------------------------------------|
| Figure 1. | Location of German Bank, southern Scotian Shelf. |
|-----------|--------------------------------------------------|

- Figure 2. MV *Anne S. Pierce* (A) profile view, (B) plan view.
- Figure 3. MV *Anne S. Pierce* at the Deep Sea Trawlers facility, Lunenburg, Nova Scotia.
- Figure 4. Afterdeck of the *Anne S. Pierce*. (A) Starboard side, (B) port side, (C) afterdeck.
- Figure 5. Computer lab of the Anne S. Pierce; images show an overlapping panorama from aft to fore (A to C). (A) Sidescan controls, (B) Hunttec controls, (C) Navigation computers.

Table 1: List of Clearwater personnel.

Title	Name
Captain	Garth Hiltz
Mate	John Langille
Chief Engineer	Byron Slauenwhite
Second Engineer	Gordon Langley
Cook	Laverne Greek
Deck Hand	Eric Robert
Deck Hand	Michael Weaver

Table 2: List of scientific personnel.

Title and duties	Name	Affiliation
Chief Scientist	Brian Todd	GSCA
Technologist (Sampling and photography)	Robert Murphy	GSCA
Technologist (Sidescan and recording systems)	Anthony Atkinson	GSCA
Technologist (Sampling and photography)	Steve MacCabe	GSCA
Technologist (Navigation)	Darrell Beaver	GSCA
Watchkeeper (Sidescan)	Peter Pledge	GSCA
Technologist (Huntec system)	Marty Uyesugi	GF

GSCA: Geological Survey of Canada (Atlantic)

GF: Geoforce

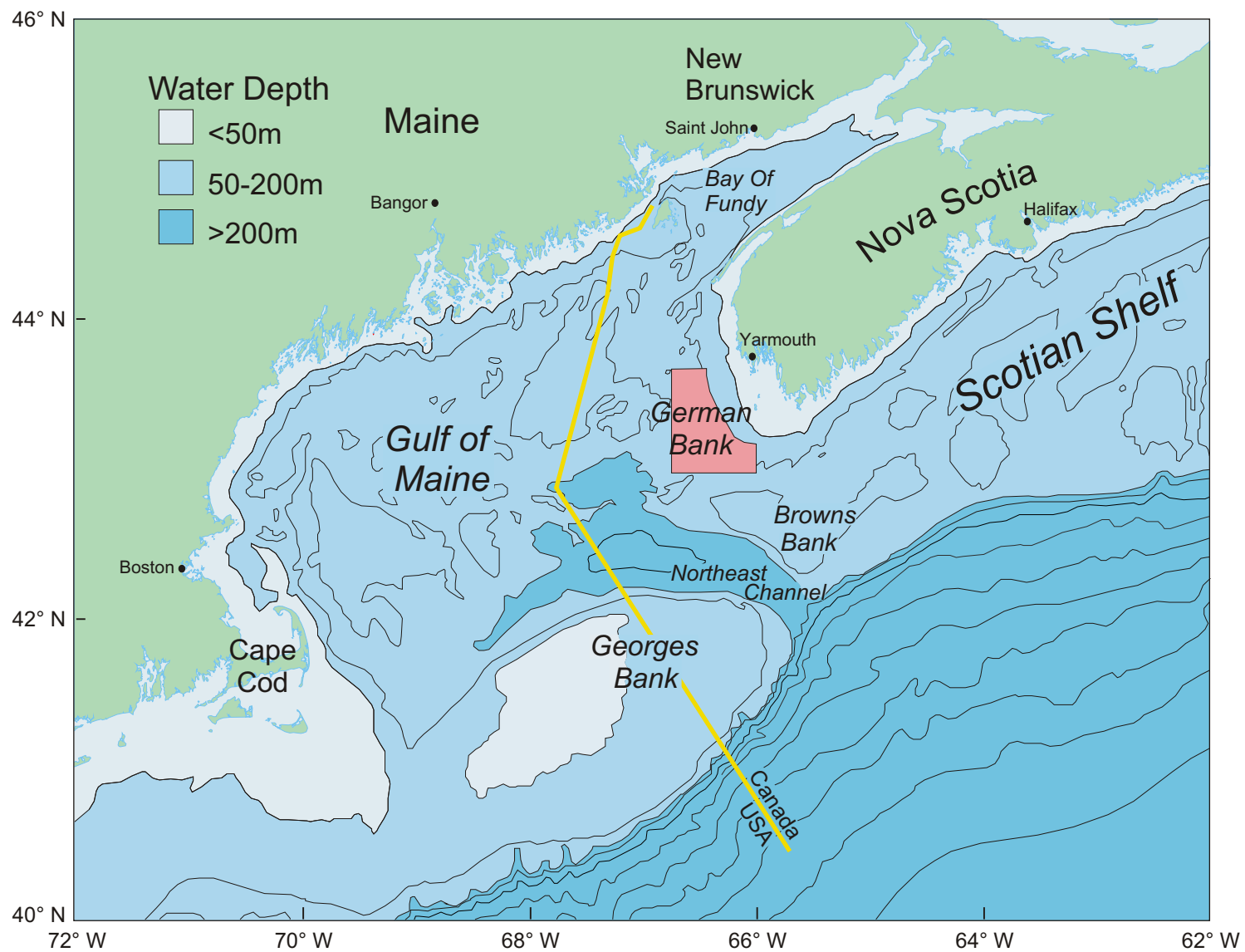


Figure 1. Location map of German Bank, southern Scotian Shelf.

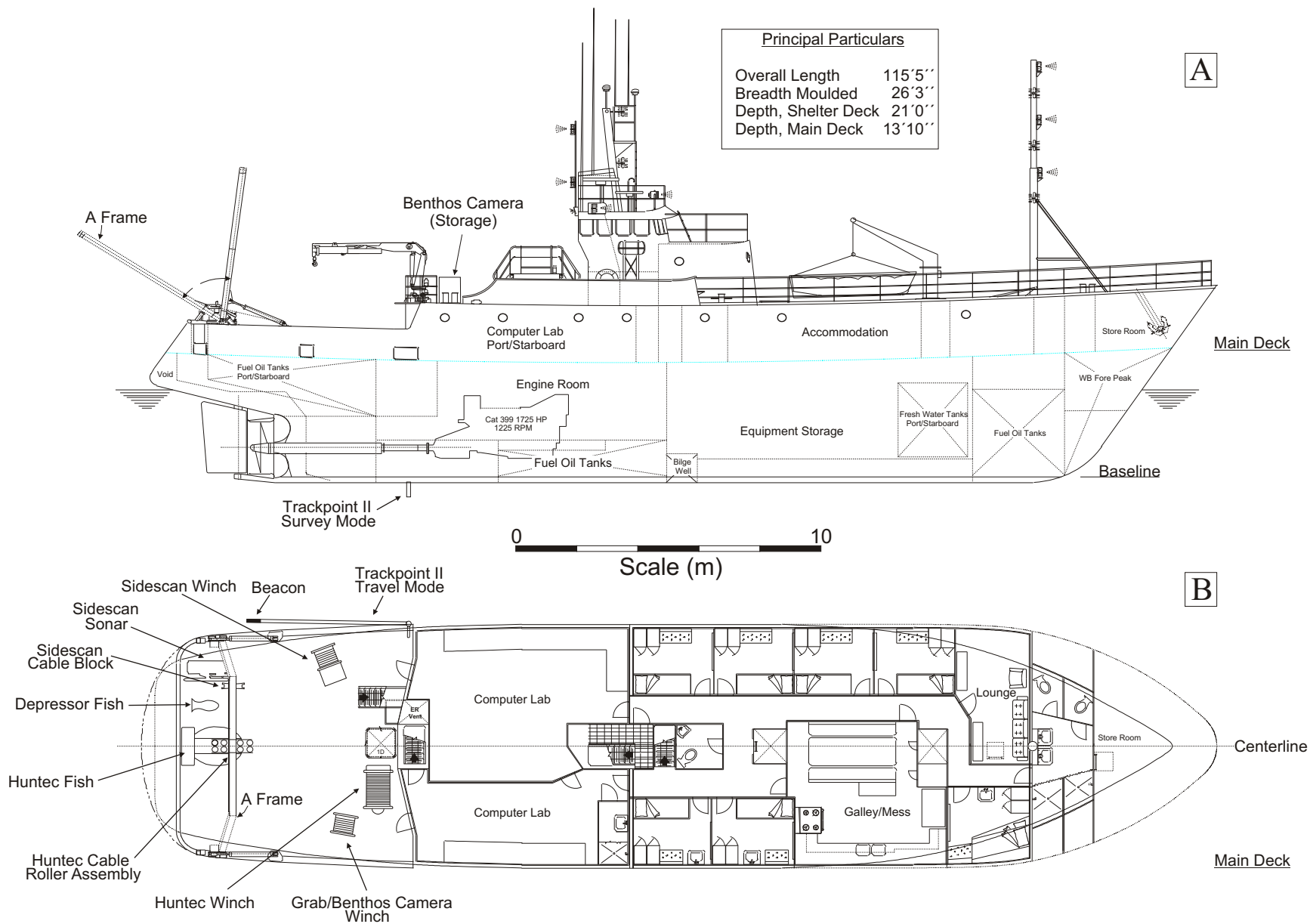


Figure 2. MV *Anne S. Pierce* (A) profile view, (B) plan view.



Figure 3. MV *Anne S. Pierce* at the Deep Sea Trawlers facility, Lunenburg, Nova Scotia.

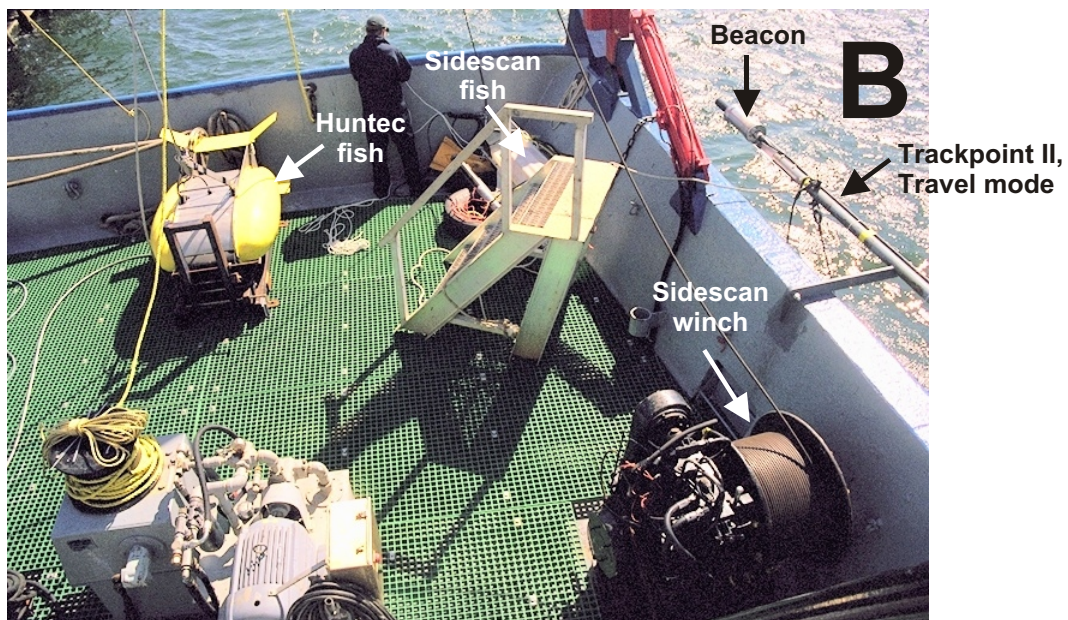
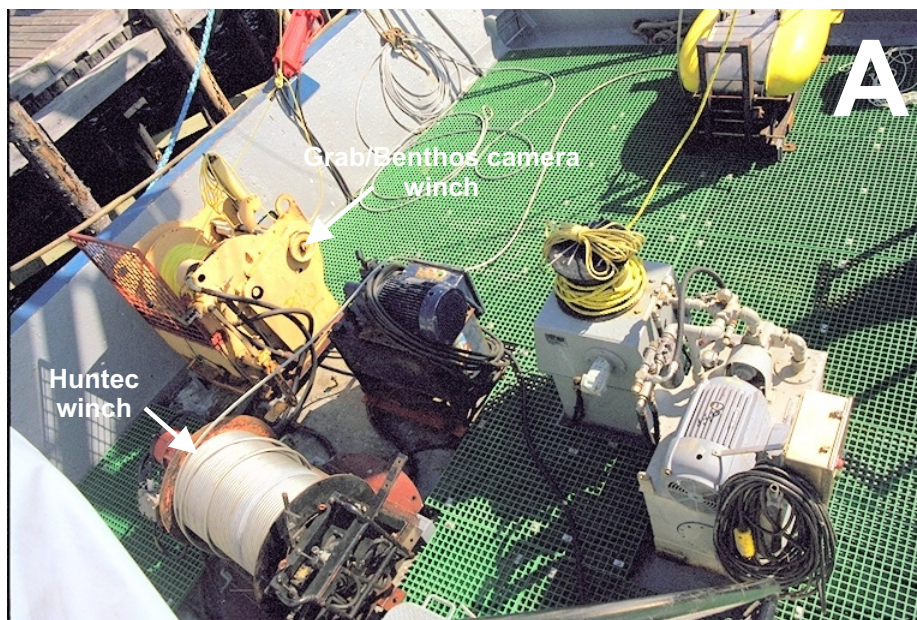


Figure 4. Afterdeck of the *Anne S. Pierce*. (A) Starboard side, (B) port side, (C) afterdeck.



Figure 5. Computer lab of the *Anne S. Pierce*; images show an overlapping panorama from aft to fore (A to C). (A) Sidescan controls, (B) Hunttec controls, (C) Navigation computers.

2. Cruise narrative - *B.J. Todd*

In this cruise narrative, all times are in Universal Time Coordinated (UTC) unless specified as Atlantic Standard Time (AST), which is three hours earlier than UTC (e.g. 1200 UTC is 0900 AST). Figure 6 shows the extent of the tracklines of the *Anne S. Pierce* on German Bank. The expedition map at a scale of 1:125,000 (Appendix 6.1) provides detailed ship's tracks and sample positions. Also depicted on this map are ships' tracks and sample sites from the *Hudson* 76-016 expedition. Line numbers referred to in the cruise narrative are labeled and day/times are shown.

Thursday, April 13 Day 104

The *Anne S. Pierce* was mobilized at Deep Sea Trawlers in Lunenburg.

Friday, April 14 Day 105

Mobilization of the ship continued at Lunenburg. The ship departed at 2000 (AST) after testing the geophysical equipment.

Saturday, April 15 Day 106

The ship arrived at German Bank at about 1000 (AST) after a very uncomfortable passage. The sea was too rough to deploy the geophysical survey equipment until the evening. Shortly after deployment on **line 100** at 2340, the sidescan sonar ceased to function and the instrument was recovered. The Huntec DTS continued to function.

Sunday, April 16 Day 107

The high seas moderated somewhat on Day 107. The sidescan remained inoperative but seismic surveying on **lines 100 to 104** was completed. **Line 100**, running to the west, was completed at 0146 and the ship altered course to the northwest on **line 101**. This line was oriented up the "valley" in the surrounding bedrock and crossed a number of prominent moraines. Course adjustments up the valley completed the line on a north heading. **Line 101** was completed at 0445 and the ship altered course to the northwest on **line 102**. This line ran to the northern edge of the multibeam survey area and was completed at 0852.

The ship altered course to the southeast and ran the short **line 103** until 0957. The ship altered course to the southwest and **line 104** was surveyed out into deep water of the Jordan Basin. At 0957, the ship altered course to the south on **line 105** and surveyed to the southern extent of the multibeam coverage. The sidescan sonar was deployed at 1450 but was retrieved with a flooded cable 10 minutes later. At 1805 on **line 105**, the Hunttec EPC malfunctioned due to overheating. Surveying continued on **line 105** until 1850 when equipment was brought onboard and the ship headed to Shelburne to be re-supplied with working EPCs from GSCA.

Monday, April 17 Day 108

The ship arrived in Shelburne at 0130 (AST). Mike Gorveatt arrived with equipment at 1200 (AST) and the ship departed Shelburne at 1300 (AST). The sidescan was tested outside Shelburne Harbour and appeared to work. The ship then proceeded to German Bank.

Tuesday, April 18 Day 109

The Hunttec survey on **line 100A** (re-survey of **line 100**) was initiated at 0157. The sidescan sonar record was very noisy; the instrument malfunctioned at 0245 and was retrieved. One of the Hunttec replacement EPCs malfunctioned at 0247, and all the equipment was retrieved in order to service the sidescan sonar. The vessel maintained position while this work was done. The sidescan sonar was deployed once again at 0413, near where the survey had previously stopped. At 0449, the ship turned north to survey line **101A** (re-survey of line 101). The sidescan sonar malfunctioned at 0705. The sidescan was retrieved and the decision was made to use the Hunttec DTS to investigate the shallow, granite outcrop on German Bank which had not yet been surveyed. **Line 111** was started near the end of **line 101A** at 0959. A short leg to the west was followed by a longer leg to the northwest. On this leg, the contact between granite outcrop and sediments was encountered at 1132. Overheating problems continued to plague the Hunttec EPC recorders. **Line 111** concluded at 1306. After a turn to the south, **Line 112** was surveyed until 1434. The Benthos camera and van Veen grab sampler were transferred from the upper afterdeck to the lower afterdeck. Eight stations (grab samples, Table 5; Benthos camera, Table 6) on sites selected near **line 105** in the deep water, western portion of the multibeam survey area were sampled (see accompanying track chart). Sampling was suspended at 2100 due to high seas.

Wednesday, April 19

Day 110

Most of the day was passed waiting for the high seas to subside. In the afternoon, the ship proceeded to the northeast corner of the multibeam survey area to find calmer water in which to test the sidescan sonar. The sidescan tests were positive and the survey equipment was deployed and operational at 2116. **Line 113** was surveyed to the southwest from shallow to deep water, repeating **line 104** from Day 107. At 2345, the Hunttec leak alarm was tripped and the instrument was offline until 2356. At 0053, the ship altered course to the south to **line 114**, repeating **line 105** from Day 107.

Thursday, April 20 Day 111

The night was very rough and uncomfortable, as well as hard on the equipment. **Line 104** was completed at 0642 and the ship turned to the east to begin **line 115** at 0650. At 0918, **line 104** was suspended due to the high sea state. The ship altered course to the northeast to **line 115A** to reduce the roll of the vessel. At 1325, the vessel altered course to the north on **line 116**, repeating **line 101** from Day 107. After a short distance, the ship altered course to the northwest to **line 117**, repeating **line 102** from Day 107. This line was completed at 1800 and the ship altered course to the southeast to begin **line 118** at 1807. This line repeats **line 103** from Day 107.

Line 118 was completed at 1903 and the ship altered course to the south-southeast to **line 119**. Although the sea state was somewhat reduced in this northeast portion of the multibeam survey area, any west-east survey pattern was not possible due to excessive ship's roll. Therefore, a zigzag line survey pattern was established to work our way westward and southward. Quite a number of lobster trap buoys were encountered along this line. **Line 119** was completed at 2035 and the ship altered course to the northwest on **line 120**. This line was completed at 2332 and the ship altered course to the southeast on **line 121**.

Friday, April 21 Day 112

In the morning, the northern zigzag pattern was completed (**lines 121 to 125**) and the ship steamed south to the central part of the survey area to do another zigzag pattern northwest of the area of bedrock outcrop (**lines 126 to 135**).

Saturday, April 22 Day 11

Line 136 transected moraines on the southern portion of the multibeam coverage. This line was completed at 0050 and the ship altered course to the northeast (**line 137**) to cross an area to the south of the multibeam coverage. The sidescan had been operational for some time, so the opportunity was seized to finally image the series of moraines on **lines 101** and **101A**. **Line 138** repeated these lines. **Line 139** to the southwest was completed as a tie to **line 111**. Finally, line 140 completed the survey at 0942.

High seas, and the prediction of even higher seas suggested that the prudent course of action was to declare the expedition complete and to *not* attempt bottom sampling. Our experience with the van Veen grab and the Benthos camera on day 109 had clearly demonstrated that the vessel was not suited for safe operations (for the instruments or the operators), given the tackle as it was arranged. This reasoning was relayed to the GSCA in Dartmouth; the situation was then discussed at length by GSCA with Clearwater in Lunenburg. Some hours later, a decision was reached between these two parties and the ship steamed for Lunenburg.

Sunday, April 23 Day 114

The ship reached the Deep Sea Trawler facility early on Sunday and the scientific staff departed. Easter Monday was a holiday and demobilization took place on Tuesday, April 25.

List of tables

- Table 3. *Anne S. Pierce* 2000 geophysical record inventory.
- Table 4. *Anne S. Pierce* 2000 digital tape start and stop times.
- Table 5. German Bank grab sample stations.
- Table 6. German Bank Benthos camera stations.

List of figures

- Figure 6. Simplified track plot of *Anne S. Pierce* 2000, German Bank. Survey lines are shown in red. Extent of multibeam coverage indicated by purple shading.

Table 3. *Anne S. Pierce* 2000 geophysical record inventory.

A. HUNTEC DTS

Survey Line	Start		End		Record Number	Comment
	Day	Time	Day	Time		
100	106	2318	107	0146	1	EPC 9800: internal hydrophone array - upper; external streamer - lower 125 ms vertical scale for each channel, 750 ms fire rate No data recorded from 2338.3-2350.1
101	107	0147	107	0445	2	EPC 9800: internal hydrophone array - upper; external streamer - lower 125 ms vertical scale for each channel, 750 ms fire rate
102	107	0445	107	0852	3	same
103	107	0852	107	0957	4	same
104	107	0957	107	1304	5	EPC 9800: external streamer to 1203, then internal hydrophone array - upper; external streamer - lower 125 ms vertical scale for each channel, 750 ms fire rate
105	107	1304	107	1805.6	6	EPC 9800: internal hydrophone array - upper; external streamer - lower 125 ms vertical scale for each channel, 750 ms fire rate EPC malfunctioned for remainder of line, from 1805.6 to 1850
100A	109	157.5	109	0247	7	EPC 8300: internal hydrophone array 125 ms vertical scale, 750 ms fire rate
	109	157.5	109	0247	8	same
111	109	0959	109	1313	9	EPC 8300: internal hydrophone array, with external streamer from 1014.5 to 1100.3 and 1147.5 to 1313 125 ms vertical scale, 750 ms fire rate

Survey Line	Start		End		Record Number	Comment
	Day	Time	Day	Time		
111	109	1059	109	1140.5	10	EPC 8300: external streamer 125 ms vertical scale, 750 ms fire rate EPC overheated and shut down
112	109	1313	109	1434	11	EPC 8300: external streamer 125 ms vertical scale, 750 ms fire rate
Test	110	2118	110	2207	12	Internal hydrophone array test
113	110	2141.5	111	0052.5	13	EPC 8300: external streamer 125 ms vertical scale, 750 ms fire rate Huntec off from 2346-2356, leak alarm
114	111	0052.5	111	0645	14	EPC 8300: external streamer 125 ms vertical scale, 750 ms fire rate
115	111	0645	111	0920	15	same
115A	111	0920	111	1147.3	16	same
	111	1148.5	111	1324.5	17	same
116	111	1324.5	111	1359	18	same
117	111	1359	111	1803		
118	111	1803	111	1851	19	same
119	111	1851	111	2040		
120	111	2040	111	2336	20	same
121	111	2336	112	0224	21	same
122	112	0224	112	0530	22	same

Survey Line	Start		End		Record Number	Comment
	Day	Time	Day	Time		
123	112	0530	112	0809	23	same
124	112	0809	112	1044	24	same
125	112	1044	112	1337	25	same
126	112	1337	112	1420	26	same
127	112	1420	112	1530		
128	112	1530	112	1628		
129	112	1628	112	1729		
130	112	1729	112	1834		
131	112	1834	112	1937		
132	112	1937	112	2030		
133	112	2030	112	2135	27	same
134	112	2135	112	2230		
135	112	2230	113	001.25		
136	113	001.25	113	0050	28	same
137	113	0050	113	0443		
138	113	0443	113	0717	29	same
139	113	0717	113	0850	30	same
140	113	0850	113	0948.2		

B. SIMRAD MS 992 SIDESCAN

Survey Line	Start		End		Record Number	Comment
	Day	Time	Day	Time		
Test	106	2240	106	2340	1	Alden 9315 recorder, very poor record, 100 m range 120 kHz (upper), 330 kHz (lower)
Test	107 ?	1720	107 ?	1805	2	Poor record, 100 m range
Test	108 ?	2135	108 ?	2205	3	Off Shelburne, 100 m range
Test	109 ?	0155	109 ?	0243	4	100 m range
100A	109	0413	109	0449	5	100 m range
101A	109	0449	109	0705		
113	110	2015	111	0053	6	Test at start of record
114	111	0053	111	0335	7	100 m range to 0105, then 200 m range
	111	0341	111	0645	8	200 m range
115	111	0645	111	0930	9	200 m range
115A	111	0930	111	1325	10	
116	111	1325	111	1356	11	200 m range
117	111	1356	111	1803		
118	111	1803	111	1853	12	200 m range
119	111	1853	111	2035		

Survey Line	Start		End		Record Number	Comment
	Day	Time	Day	Time		
120	111	2035	111	2333	13	200 m range
121	111	2333	112	0220	14	200 m range
122	112	0220	112	0534.75	15	200 m range
123	112	0536.75	112	0806	16	200 m range
124	112	0806	112	1041		
125	112	1041	112	1335	17	200 m range
126	112	1335	112	1420		
127	112	1420	112	1528		
128	112	1528	112	1628		
129	112	1628	112	1727	18	200 m range
130	112	1727	112	1834		
131	112	1834	112	1937		
132	112	1937	112	2031		
133	112	2031	112	2135	19	200 m range
134	112	2135	112	2227		
135	112	2227	113	0000		
136	113	0000	113	0050	20	200 m range
137	113	0050	113	0440		

Survey Line	Start		End		Record Number	Comment
	Day	Time	Day	Time		
138	113	0440	113	0713.75	21	200 m range
139	113	0715.7	113	0848	22	200 m range
140	113	0848	113	0958.4		

Table 4: *Anne S. Pierce 2000* digital tape start and stop times.

Instrument	Tape Number	Start day/time	End day/time	File nos.	Lines	Mammoth Tape #40 File Nos.
Huntec DTS	1	107 / 0014	107 / 0059	1	100	111
	2	107 / 0102	107 / 0204	1-4	100-101	113-116
	3	107 / 0208	107 / 0645	1-6	101-102	118-123
	4	107 / 0654	107 / 0755	1-2	102	125-126
	5	107 / 0820	107 / 1920	1-15	102-105	128-142
	6	109 / 0215	109 / 1433	1-9	100A-112	144-152
	7	110 / 2204	112 / 1335	3-57	113-125	154-210
	8	112 / 1338	113 / 0942	1-40	126-140	212-251
Sidescan*	1	109 / 0215	109 / 0245	1	100A	2
	2	109 / 0437	109 / 0709	1-4	100A-101A	4-7
	3	110 / 2204	111 / 1559	4-27	113-117	9-35
	4	111 / 1605	112 / 0530	1-21	117-122	37-57
	5	112 / 0537	113 / 0441	1-41	123-137	59-99
	6	113 / 0454	113 / 0942	1-9	138-140	101-109

* Note that the tape channels assignments for sidescan sonar tapes 1-3 and tape 4, files 1-8, are as follows:

1: 120 kHz starboard 2: 120 kHz port 3: 330 kHz port 4: 330 kHz starboard

For tape 4, files 9-21, and tapes 5 and 6, the channel assignment are as follows:

1: 120 kHz port 2: 120 kHz starboard 3: 330 kHz port 4: 330 kHz starboard

Table 5. German Bank grab sample stations.

Station No.	Day/Time (UTC)	Latitude (°N)	Longitude (°W)	Water Depth (m)	Comments
1	109/1557	43.39335	66.729725	160	2 nd try at 109/1604, 43.392352 N, 66.730125 W ; very little sediment, two vials filled, no photo taken
2	109/1622	43.395242	66.731259	160	same location as station 1; again two vials of sediment
5	109/1822	43.374005	66.753134	124	1 st try; one rock, no sediment 2 nd try at 109/1829, 43.374339 N, 66.753893 W, gravel and sand
6	109/1855	43.36319	66.745034	142	mud with some sand, abundant macrofauna; located in “crater”
8	109/2054	43.27292	66.708555	93	1 st try: no sample, too much swell; 2 nd try: same result

Table 6. German Bank Benthos camera stations.

Station No.	Start Day/Time (UTC)	Start Lat/Long	Stop Day/Time (UTC)	Stop Lat/Long	Water Depth (m)	Comments
3	109/1716	43.396163 66.727760	109/1721	43.395417 66.727970	?	14 photos
4	109/1801	43.374312 66.753866	109/1807	43.374491 66.753002	155	13 photos
7	109/1921	43.363723 66.744437	109/1927	43.363293 66.745054	121	22 photos

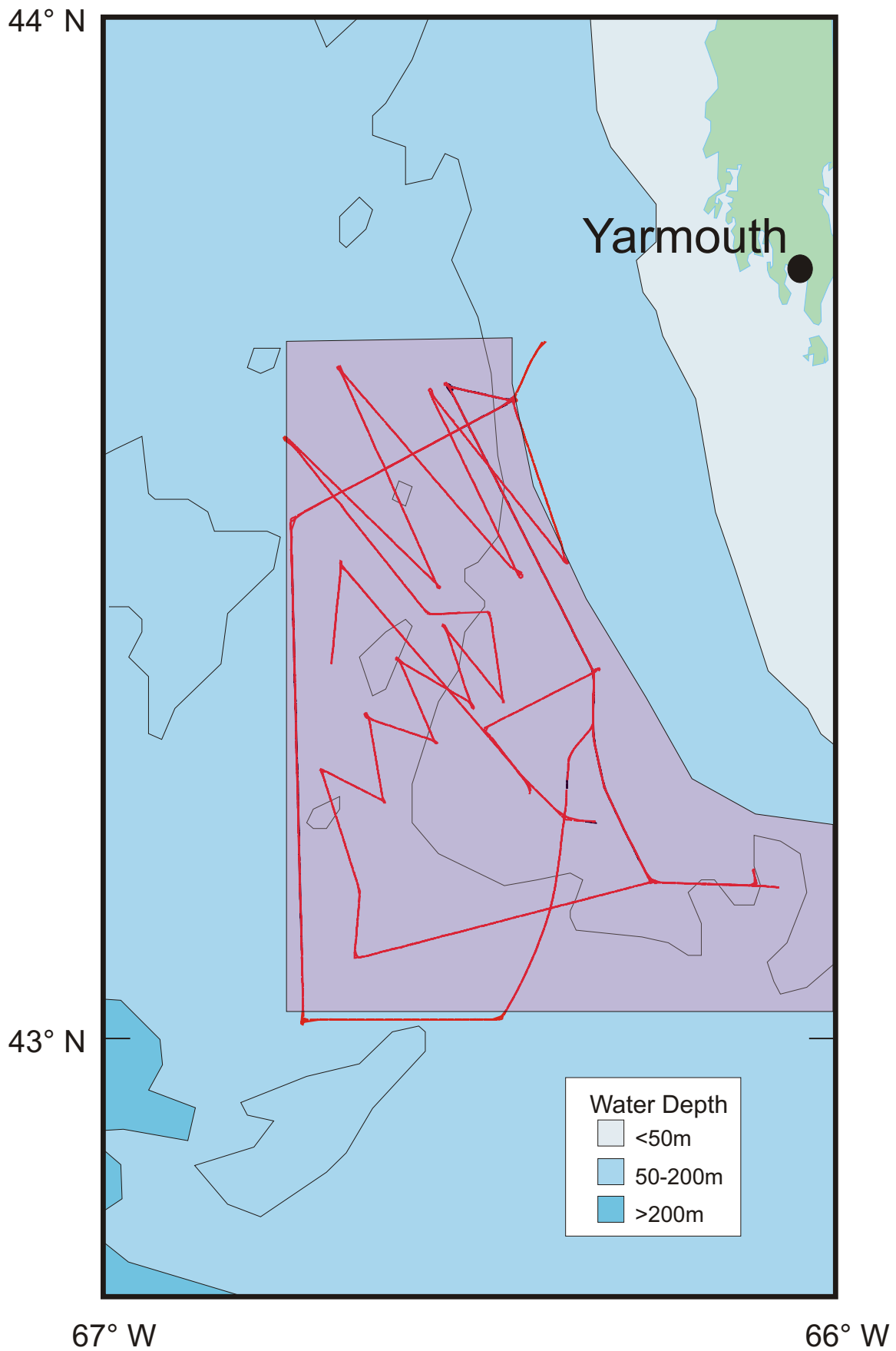


Figure 6. Simplified trackplot of *Anne S. Pierce* 2000, German Bank. Survey lines are shown in red. Extent of multibeam bathymetric coverage indicated by purple shading. The detailed trackplot in Appendix 6.1 includes line number designations, day/times and sample locations.

3. Navigation and positioning - *D.E. Beaver*

3.1 AGCNav and Regulus

Navigation during the 2000 *Anne S. Pierce* cruise to German Bank was accomplished using Regulus (with AGCNav backup logger) navigation computer programs which receive input via the serial port in the form of standard NMEA strings. The equipment used to generate the NMEA strings included POSMV and an ultra-short baseline acoustic positioning system (ORE Trackpoint II). All NMEA strings were fed into a Baytech multiplexer and then sent to a Black Box splitter. This signal was then fed to the AGCNav backup logger as well as to Regulus. The signal was also sent to the Huntec and sidescan sonar AGCDIG.

The following NMEA strings were used for positioning of the vessel and towed bodies, and were logged for post-processing:

- \$INGGA: GPS time, latitude and longitude of the GPS antenna in the WGS-84 coordinate system, and various GPS satellite information fields
- \$INHDT: Heading of vessel relative to true north
- \$INVTG: Course over ground in degrees, speed over ground in knots
- \$POREB: Proprietary string created by AGCNav which handles ORE Trackpoint II data including, towfish depth, slant range, and bearing
- \$POREP: Created by AGCNav to display towfish position
- \$SODBT: Depth below transducer in feet, meters, fathoms

Regulus was set up in the lab with a video split of the master station, meaning that it received the NMEA strings and displayed the vessel location (and the location of the two towed bodies). The AGCNav computer on the bridge was used solely as a backup.

The logging of the navigation data was done on one AGCNav laptop and on Regulus. AGCNav and Regulus have a file naming convention based on the ship's name, Julian day, and file number that day. An example would be ANNE109A.00E, where ANNE are the first four letters of the ship's name, 109 is the Julian day, and "A" means it was the first file created on day 109. Each day the navigation data was backed up from both logging computers onto CD-ROM on the master computer. The raw navigation files (.00E) were converted to files which contain only time, latitude and longitude (.00A) using ETOA file

conversion software. The .00A files were then plotted using the program APLOT to view the navigation and to ensure that there were no data gaps. If data gaps were found, the data from the backup logger was used to fill the gaps. The navigation files are provided in Appendix 6.2.

3.2 ORE Trackpoint II

A 3° horizontal offset to starboard was entered into the Trackpoint based on the observed bias. Visual inspection during towfish deployment agreed with this adjustment. Two transponders were tracked simultaneously in ORE's Fish Track mode: one was fitted to the Hunttec DTS (transponder 6, transmit frequency of 19 kHz and receive frequency of 22 kHz) and the other to the Simrad 992 sidescan sonar (transponder 3, transmit frequency of 17 kHz and receive frequency of 26 kHz).

4. Geophysical survey

4.1 Overview - *B.J. Todd*

Pre-cruise planning and daily refinement of the ship's geophysical survey tracks on the *Anne S. Pierce* cruise were based on careful study of the multibeam bathymetric and backscatter data provide by the Canadian Hydrographic Service. Targets and selected areas identified on these data sets were traversed by the ship using differential GPS for accurate navigation. The advantage that the multibeam data provides to enhance the usefulness of the conventional geophysical survey profiles cannot be overemphasized.

The objective of the geophysical survey was to collect regional geophysical survey lines across German Bank and to infill and augment data collected during the regional 1982 *Fogo Isle* cruise, and CSS *Dawson* 89-001 and CSS *Hudson* 92-01 cruises on northern Georges Bank. To this end, 1847 km of Huntect DTS and sidescan sonar data were collected (Fig. 6, Appendix 6.1). The data were output on graphic recorders (Table 3) and, simultaneously, digitally recorded (Table 4, Figure 7). Data were of medium to high quality, due to the changeable sea state during the survey period.

4.2 Sidescan sonar system - *A. Atkinson*

The sidescan sonar system used on the *Anne S. Pierce* was the Simrad MS992 neutral tow system. This system produced outstanding results even in rough weather. Data quality and quantity suffered in the early days of the cruise because of numerous flooded underwater splices and cable problems.

Records were displayed at a 200 metre range (100 m per channel) and every attempt was made to keep the tow vehicle close enough to the bottom to produce good acoustic shadows of bottom features. Fish height was ideally 18 to 25 metres above the seabed. Data was logged on an AGCDIG digital data logger. During the first day of the survey there was some experimentation with the vessel's tow speed. One night was spent jogging the vessel in and out of gear to try to keep the speed on line to about 4 knots. While this produced good imaging, it was hard to steer a straight course and the speed along track varied substantially. It was decided to run the subsequent lines at "idle speed" which translated to a steady speed between 5 and 6 knots, depending on the direction of the tidal currents.

Suggestions for improvement:

The same winch that was used on the *Hamilton Banker* 1999 expedition to Georges Bank was prepared for the *Anne S. Pierce* mission. When it was learned that the cable was too short to work in German Bank water depths of 170 meters another winch with a 600 metre cable had to be substituted.

Procedures for underwater splices used on this system are under review. All splices we attempted to use had been extensively used in the previous field season. Although they passed shallow water tests, they rapidly flooded at depth under real survey conditions. A more robust splicing system is being developed.

There were some minor power and ground problems with the ship's electrical system. Some of the Uninterruptible Power Supply's plugs had the large pin at high potential and the small pin at low potential. This is opposite to conventional wiring on land-based installations. Both pins should either be floating, or the large pin should be low and the small should be high. This could cause a "hot ground" in some survey equipment. Regular non-UPS plugs also had some problems. Plugs wired to the new panel seemed to produce noise on the equipment while the original plugs (old and tinged with paint) worked well.

Before the recording of file 8 on tape 4, the following data logger channel convention was used:

Data Logger Channels	Simrad MS992 Channels Recorded
CH1	Right 120 KHz
CH2	Left 120 KHz
CH3	Left 330 KHz
CH4	Right 330 KHz

After this file, the convention was switched to:

Data Logger Channels	Simrad MS992 Channels Recorded
CH1	Left 120 KHz
CH2	Right 120 KHz
CH3	Left 330 KHz
CH4	Right 330 KHz

4.3 Hunttec Deep Tow System - *M. Uyesugi*

Equipment description - The PGC Hunttec DTS system was used on this cruise (Tables 7, 8, 9; Fig. 7). The maximum power output of this system is 540 joules (30 mfd storage capacitance) with an ED10 F/C Boomer and multi tip sparker source. The internal single-element LC10 hydrophone was configured as Seismic #1. The externally-towed Benthos Mesh 15/10P streamer hydrophone was connected as Seismic #2 (Table 7).

The ED10 boomer source is depth-compensated and outputs a highly repeatable broadband pulse, capable of resolving 10 centimetres vertically. Peak output intensity is 118 db relative to 1 micro bar at 1 metre, with a pulse duration of 110 microseconds. The sparker source has twenty, # 22 awg, solid core tips. Sparker peak amplitude and pulse width are depth dependant.

The deck equipment consisted of a Hunttec Model 1000 Oceanographic winch, which included a multi-way slip ring and a 305 metre, fourteen conductor, armoured tow cable. The winch was powered by the SSS 220 VAC, 25 HP hydraulic pump unit. The tow cable was handled by a 36 inch diameter roller cluster rigged on the centre position of the aft A-frame.

The lab instrumentation consisted of the Hunttec Systems Console and DC high voltage power supply (PCU). The Systems Console houses the Bottom Motion Compensator circuits, the +24 volt fish supply, and modules for signal processing and tape outputs. The Hunttec Mk III PCU provides DC power to the boomer in switchable ranges from 2 to 6 kilovolts.

Graphic display and signal processing - The two Hunttec seismic channels were displayed on a EPC 9800 dual channel recorder. Seismic #1 (internal LC10 hydrophone) was processed by the systems console's Adaptive Signal Processor (ASP) module and then displayed on Channel A of the EPC recorder. Seismic #2 (external streamer) was passed through a Krohn-Hite filter with a low pass setting of 3500 hertz, for display on Channel B of the EPC recorder.

Data recording - The Hunttec signals were recorded on the AGCDIG unit #2: a digital, four channel logger with 8700 Exabyte tape drive (software version 2.33) (Table 7).

Equipment performance - The only Hunttec system problem was a required retermination on

Day 285 after loss of external steamer signal made gear recovery necessary. It was noted that about ten outer strands of armour cable were broken. This may have occurred after snagging fishing gear on Day 281, combined with cable strumming.

AGCDIG - The AGCDIG program locked occasionally causing an increase in tape use.

Data quality - The boomer source was used exclusively during the survey. In general, Hunttec data quality was good. Occasional cable strumming caused objectionable noise on the internal hydrophone channel. The external steamer had to be checked a couple of times resulting in the underwater E/O connectors being regreased to eliminate intermittent data.

Recommendations

- 1) The PGC winch should be modified for remote operation.
- 2) The fourteen-conductor armoured tow cable performed well, even after a snagged rope bent the cable severely at the towpoint. After several days, and significant cable strumming due to a lack of cable fairing, the tow cable had to be reterminated. At the conclusion of the survey, the tow cable had one broken strand in the outer armour; the cable should be reterminated and have cable fairing applied.
- 3) The intermittent external steamer did not need to be regreased after the retermination but the old steamer's E/O connection is worn and is suspect. The steamer's tail rope was cut off by the ship's prop and the tail rope and drogue were replaced. Damage to the steamer was not evident but replacing the E/O connection would be advisable.
- 4) The EPC 9800 had paper feed problems which were fixed by adjusting the machine.
- 5) Running the Hunttec and sidescan systems on the same power pack is not advisable and data quality is compromised.
- 6) The roller cluster lost the top bolt on the starboard side and caused excessive wear on the large roller. The large roller should be removed, repaired and/or replaced.

4.4 Digital tape recording - *P.E. Pledge*

The AGCDIG for both sidescan and Hunttec had only one problem. The DIG software often locked at the time of a file change (i.e. the automatic hourly change or manual change). The malfunction occurred more frequently on the Hunttec DIG (unit #2). All of the serial data from the MUX going into AGCNav was also passed into DIG for logging. This did not appear to cause any problems. After each tape was removed, the "set clock" utility was

executed and the drives were cleaned.

List of tables

Table 7. Hunttec DTS equipment.

Table 8. Equipment settings.

Table 9. Data recording parameters.

List of figures

Figure 7. Schematic of Simrad sidescan sonar (upper) and Hunttec DTS (lower) systems on the *Anne S. Pierce*.

Table 7. Hunttec DTS equipment.

Unit description	Serial Number
Tow Fish Body	PGC
ED10F/C Boomer Source	2015
MK5-2 Attitude Sensor Unit	N/A
S500 Energy Storage Unit	1017
Internal LC 10 Hydrophone	N/A
External Benthos 15/10P Streamer	103
Hunttec Oceanographic Winch and Power Pack	---
Roller Cluster 36" Dia.	---
Systems Console	102
EPC 9800 Graphic Recorder	104
MK 3 Power Control Unit	120
Krohn-Hite 3550R Filter	N/A
AGCDIG Data Logger	#2

Table 8. Equipment settings.

Parameter	Setting
Fire rate	1.0 sec
PCU power setting	4 kilovolts (240 joules)
ESU power setting	30 microfarad (540 joules max.)
BMC (motion compensation)	Pressure Mode
Display Gain	Seismic #1- Adaptive. Seismic #2- Max. EPC gain
Filter Setting - Internal - External	Seismic #1 - 500 - 6000 hertz Seismic #2 - 300 - 3500 hertz
Processor Gain (System Console)	4 kV int. / 2 kV ext
DTS source	Boomer
AGCDIG sample rate	60 to 110 microsecond
AGCDIG samples per channel	4096
AGCDIG base gain A/D board	4
EPC sweep speed	125, 250, 500 microsecond
EPC print polarity	positive

Table 9. Data recording parameters.

AGCDIG Inputs	Description
Ch. #1	Seismic #1 - Internal LC10 hydrophone
Ch. #2	Seismic #2 - External Benthos 15/10P streamer
Trigger	Print delay trigger

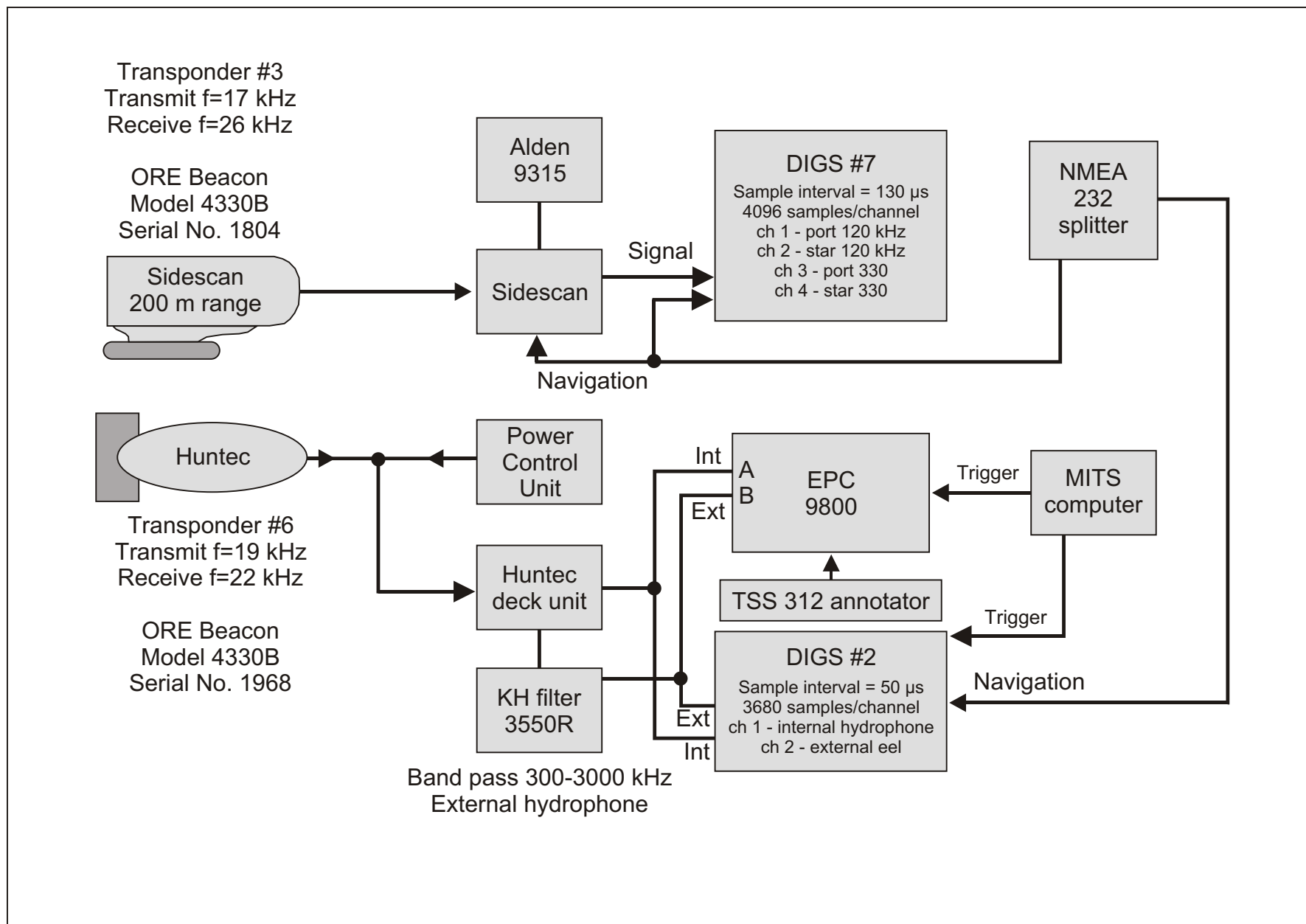


Figure 7. Schematic of Simrad sidescan sonar (upper) and Hunttec DTS (lower) systems on the *Anne S. Pierce*.

5. Geological sampling - *B.J. Todd and R. Murphy*

A van Veen grab sampler with a capacity of approximately 0.01 m³ was used to obtain samples from the sea floor (Table 5). The van Veen grab was deployed over the stern using the starboard winch and the A-frame. Five stations were attempted with material retrieved at four stations (see photos in Appendix 6.4). These sites were selected for sampling on the basis of the multibeam and/or geophysical information.

Sample volumes were not satisfactory. The van Veen was able to obtain only small volumes. This may have been exacerbated by rough sea conditions and strong currents; the angle of the winch cable was, more often than not, far off vertical. Therefore, the instrument may not have tripped on the sea floor in a manner most suited to sediment retrieval. As well, the winch speed was relatively slow and the van Veen impacted the seabed slowly. To ensure more complete sediment retrieval on future German Bank surveys, an IKU grab (which is much larger and heavier) is recommended, accompanied by a faster, dedicated winch.

The same deployment difficulties were experienced with the Benthos camera (Table 6). Photographs were obtained at three stations (see Appendix 6.5). The freeboard surrounding the afterdeck made deployment and retrieval somewhat dangerous for the operators and for the equipment. It is recommended that the Benthos camera not be deployed from the afterdeck of the *Anne S. Pierce* unless alterations are made to the vessel.